

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6	RISK REDUCTION				
6.1	<p>General</p> <p>The objective of <u>risk reduction</u> can be <u>achieved by the elimination of hazards</u>, or by separately <u>or simultaneously reducing</u> each of the two elements that determine the associated risk:</p> <ul style="list-style-type: none"> - severity of <u>harm</u> from the hazard under consideration; - <u>probability of occurrence</u> of that harm. <p>All <u>protective measures</u> intended for reaching this objective shall be applied <u>in the following sequence</u>, referred to as the three-step method</p> <p>Step 1: <u>Inherently safe design</u> measures</p> <p>Step 2: <u>Safeguarding and/or complementary protective measures</u></p> <p>Step 3: <u>Information for use</u></p>				
6.2	Inherently safe design measures				
6.2.1	<p>General</p> <p>“Inherently safe design measures are achieved by avoiding hazards or reducing risks by a suitable choice of design features for the machine itself and/or interaction between the exposed persons and the machine.”</p>				

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6.2.2	Consideration of geometrical factors and physical aspects				
6.2.2.1	Geometrical factors Such factors include the following:				
	a) The form of machinery is designed to maximize direct <u>visibility of the working areas and hazard zones from the control position</u> — reducing blind spots, for example — and choosing and locating means of indirect vision where necessary (mirrors, etc.) so as to take into account the characteristics of human vision, particularly when safe operation requires permanent direct control by the operator, for example: <ul style="list-style-type: none"> - the travelling and working area of mobile machines; - the zone of movement of lifted loads or of the carrier of machinery for lifting persons - the area of contact of the tool of a hand-held or hand-guided machine with the material being worked. The design of the machine shall be such that, from the main control position, the operator is able to ensure that there are no exposed persons in the danger zones.	P			
	b) The form and the relative location of the mechanical components parts: for instance, crushing and shearing hazards are avoided by increasing the minimum <u>gap between the moving parts, such that the part of the body under consideration can enter the gap safely, or</u> by reducing the gap so that <u>no part of the body can enter it</u> (see ISO 13854 and ISO 13857).	P			
	c) <u>Avoiding sharp edges</u> and corners, protruding parts: in so far as their purpose allows, accessible parts of the machinery shall have no sharp edges, no sharp angles, no rough surfaces, no protruding parts likely to cause injury, and no openings which can “trap” parts of the body or clothing. In particular, sheet metal edges shall be deburred, flanged or trimmed, and open ends of tubes which can cause a “trap” shall be capped.	P			
	d) The form of the machine is designed so as to achieve a <u>suitable working position and provide accessible manual controls</u> (actuators).	P			

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6.2.2.2	Physical aspects Such aspects include the following:				
	a) <u>limiting</u> the <u>actuating force</u> to a sufficiently low value so that the actuated part does not generate a mechanical hazard;	P			
	b) <u>limiting</u> the <u>mass and/or velocity</u> of the movable elements, and hence their kinetic energy;	P			
	c) <u>limiting the emissions</u> by acting on the characteristics of the source using measures for reducing;				
	1) <u>noise emission</u> at <u>source</u> (see ISO/TR 11688-1),	P			See 3154012.50A
	2) the emission of <u>vibration at source</u> , such as redistribution or addition of mass and changes of process parameters [for example, frequency and/or amplitude of movements (for hand-held and hand-guided machinery, see CR 1030-1)],	P			See 3154012.50A
	3) the emission of <u>hazardous substances</u> , including the use of less hazardous substances or dust-reducing processes (granules instead of powders, milling instead of grinding), and	P			
	4) <u>radiation</u> emissions, including, for example, avoiding the use of hazardous radiation sources, limiting the power of radiation to the lowest level sufficient for the proper functioning of the machine, designing the source so that the beam is concentrated on the target, increasing the distance between the source and the operator or providing for remote operation of the machinery [measures for reducing emission of non-ionizing radiation are given in 6.3.4.5 (see also EN 12198-1 and EN 12198-3)].			N/A	

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6.2.3	Taking into account general technical knowledge of machine design				
	This general technical knowledge can be derived from technical specifications for design (standards, design codes, calculation rules, etc.), which should be used to cover				
	a) <u>mechanical stresses</u> such as				
	- stress limitation by implementation of <u>correct calculation</u> , construction and fastening methods as regards, for example, bolted assemblies and welded assemblies,	P			
	- <u>stress</u> limitation by <u>overload prevention</u> (bursting disk, pressure-limiting valves, breakage points, torque-limiting devices, etc.),	P			
	- <u>avoiding fatigue</u> in elements under variable stresses (notably cyclic stresses), and	P			
	- static and dynamic <u>balancing of rotating elements</u> ,	P			
	b) <u>materials and their properties</u> such as				
	- resistance to corrosion, ageing, abrasion and wear,	P			
	- hardness, ductility, brittleness,	P			
	- homogeneity,	P			
	- toxicity, and	P			
	- flammability.	P			
	c) <u>emission values</u> for				
	- noise,	P			69,0 dB(A)
	- vibration,	P			1,6 m/s ²
	- hazardous substances, and			N/A	
	- radiation.			N/A	
	When the reliability of particular components or assemblies is critical for safety (for example, ropes, chains, lifting accessories for lifting loads or persons), stress limits shall be multiplied by <u>appropriate working coefficients</u> .				

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6.2.4	Choice of appropriate technology				
	One or more hazards can be eliminated or risks reduced by the choice of the technology to be used in certain applications such as the following:				
	a) on machines intended for use in <u>explosive atmospheres</u> , using				
	- appropriately selected <u>pneumatic or hydraulic control</u> system and machine actuators,			NA	
	- <u>intrinsically safe electrical equipment</u> (see IEC 60079-11);	P			
	b) <u>for particular products</u> to be processed (for example, by a solvent), by using <u>equipment</u> that ensures the <u>temperature will remain far below</u> the flash point;	P			
	c) the use of alternative <u>equipment to avoid high noise levels</u> , such as			NA	
	- electrical instead of pneumatic equipment,				
	- in certain conditions, water-cutting instead of mechanical equipment				
6.2.5	Applying principle of positive mechanical action				
	<u>Positive mechanical</u> action is achieved when a moving mechanical component inevitably moves another component along with it, either by direct contact or via rigid elements. An example of this is positive opening operation of switching devices in an electrical circuit (see IEC 60947-5-1 and ISO 14119).	P			
	NOTE Where a mechanical component moves and thus allows a second component to move freely (for example, by gravity or spring force), there is no positive mechanical action of the first component on the second.				

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6.2.6	Provisions for stability				
	Machines shall be designed so that they have <u>sufficient stability</u> to allow them to be used safely in their specified conditions of use. Factors to be taken into account include				
	- the geometry of the <u>base</u> ,	P			
	- the <u>weight distribution</u> , including loading,	P			
	- the <u>dynamic forces</u> due to movements of parts of the machine, of the machine itself or of elements held by the machine which can result in an overturning moment,	P			
	- <u>vibration</u> ,	P			
	- <u>oscillations</u> of the centre of gravity,			N/A	
	- characteristics of the <u>supporting surface in case of travelling or installation on different sites</u> (ground conditions, slope, etc.), and	P			
	- <u>external forces</u> , such as wind pressure and manual forces.	P			
	Stability shall be considered in all phases of the life cycle of the machine, including handling, travelling, installation, use, dismantling, disabling and scrapping.				
6.2.7	Provisions for maintainability				
	When designing a machine, the following maintainability factors shall be taken into account <u>to enable maintenance</u> of the machine:				
	- accessibility, taking into account the environment and the human body measurements, including the dimensions of the working clothes and tools used;	P			
	- ease of handling, taking into account human capabilities;	P			
	- limitation of the number of special tools and equipment.	P			

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6.2.8	<p>Observing ergonomic principles Ergonomic principles shall be taken into account in designing machinery so as to <u>reduce</u> the <u>mental</u> or <u>physical</u> stress of, and strain on, the operator. These principles shall be considered when allocating functions to operator and machine (degree of automation) in the basic design.</p> <p>NOTE Also improved are the performance and reliability of operation and hence the reduction in the probability of errors at all stages of machine use.</p> <p>Account shall be taken of <u>body sizes</u> likely to be found in the intended user population, <u>strengths</u> and <u>postures</u>, <u>movement amplitudes</u>, frequency of <u>cyclic actions</u> (see ISO 10075 and ISO 10075-2).</p> <p>All elements of the <u>operator-machine interface</u>, such as controls, signalling or data display elements, shall be designed to be <u>easily understood</u> so that clear and unambiguous interaction between the operator and the machine is possible. See EN 614-1, EN 13861 and IEC 61310-1.</p> <p>The designer's attention is particularly drawn to following ergonomic aspects of machine design.</p>				
	a) <u>Avoid</u> the necessity for <u>stressful postures and movements</u> during the use of the machine (for example, providing facilities to adjust the machine to suit the various operators).	P			
	b) Design machines, especially hand-held and mobile machines, so as to enable them to be <u>operated easily</u> , taking into account human effort, actuation of controls and hand, arm and leg anatomy.	P			
	c) <u>Limit</u> as far as possible <u>noise</u> , <u>vibration</u> and thermal effects such as <u>extreme temperatures</u> .			N/A	
	d) <u>Avoid linking</u> the <u>operator's working rhythm</u> to an automatic succession of <u>cycles</u> .	P			
	e) <u>Provide</u> local <u>lighting</u> on or in the machine for the illumination of the working area and of adjusting, setting-up and frequent <u>maintenance zones</u> when the design features of the machine and/or its guards render the ambient lighting inadequate. Flicker, dazzling, shadows and stroboscopic effects shall be avoided if they can cause a risk. If the position or the lighting source has to be adjusted, its location shall be such that it does not cause any risk to persons making the adjustment.			N/A	

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	f) Select, locate and identify manual controls (actuators) so that				
	- they are clearly <u>visible and identifiable</u> , and appropriately marked where necessary (see 6.4.4),	P			
	- they can be <u>safely operated without hesitation</u> or loss of time and without ambiguity (for example, a standard layout of controls reduces the possibility of error when an operator changes from a machine to another one of similar type having the same pattern of operation),	P			
	- their <u>location</u> (for push-buttons) <u>and</u> their <u>movement</u> (for levers and hand wheels) are <u>consistent with their effect</u> (see IEC 61310-3), and	P			
	- their operation <u>cannot cause</u> additional <u>risk</u> . See also ISO 9355-3.	P			
	<u>Where a control</u> is designed and constructed to <u>perform</u> several <u>different actions</u> — namely, where there is no one-to-one correspondence (for example, keyboards) — the action to be performed <u>shall be clearly displayed</u> and subject to confirmation where necessary.			N/A	
	<u>Controls</u> shall be so arranged that their layout, travel and resistance to operation are <u>compatible with the action to be performed</u> , taking account of ergonomic principles. Constraints due to the necessary or foreseeable use of personal protective equipment (such as footwear, gloves) shall be taken into account.	P			
	g) Select, <u>design and locate indicators</u> , dials and visual display units so that				
	- they <u>fit</u> within the parameters and characteristics of <u>human perception</u> ,				
	- <u>information</u> displayed can be <u>detected, identified and interpreted</u> conveniently, i.e. long-lasting, distinct, unambiguous and understandable with respect to the operator's requirements and the intended use, and	P			
	- the operator is able to <u>perceive</u> them <u>from the control position</u> .	P			
6.2.9	Electrical hazards				
	For the design of the electrical equipment of machines, IEC 60204-1 gives general provisions about <u>disconnection</u> and <u>switching</u> of electrical circuits and for <u>protection against electric shock</u> . For requirements related to specific machines, see corresponding IEC standards (for example, IEC 61029, IEC 60745 or IEC 60335).	P			Earthing connection and class II construction.

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6.2.10	Pneumatic and hydraulic hazards Pneumatic and hydraulic equipment of machinery shall be designed so that				
	- the <u>maximum rated pressure cannot be exceeded</u> in the circuits (using, for example, pressure-limiting devices),			N/A	
	- <u>no hazard results from pressure fluctuations</u> or increases, or from loss of pressure or vacuum,			N/A	
	- <u>no hazardous fluid jet or sudden hazardous movement</u> of the hose (whiplash) results <u>from leakage</u> or component failures,			N/A	
	- <u>air</u> receivers, air reservoirs or similar <u>vessels</u> (such as in gas-loaded accumulators) <u>comply with</u> the applicable design standard <u>codes</u> or regulations for these elements,			N/A	
	- all elements of the equipment, especially pipes and hoses, are <u>protected against harmful external effects</u> ,			N/A	
	- as far as possible, reservoirs and similar <u>vessels</u> (for example, gas-loaded accumulators) are <u>automatically depressurized when isolating</u> the machine <u>from its power supply</u> (see 6.3.5.4) and, if not possible, means are provided for their isolation, local depressurizing and pressure indication (see also ISO 14118:2000, Clause 5), and			N/A	
	- all <u>elements which remain under pressure after isolation</u> of the machine from its power supply are <u>provided with</u> clearly identified <u>exhaust devices</u> , and there is a warning label drawing attention to the necessity of depressurizing those elements before any setting or maintenance activity on the machine.			N/A	

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6.2.11	Applying inherently safe design measures to control systems				
6.2.11.1	General The design measures of the control system shall be chosen so that their safety-related performance provides a sufficient amount of risk reduction (see ISO 13849-1 or IEC 62061).				
6.2.11.2	Starting of an internal power source/switching on an external power supply				
	The <u>starting</u> of an internal <u>power source</u> or switching-on of an external power supply shall <u>not result in a hazardous situation</u> . For example: - starting the internal combustion engine shall not lead to movement of a mobile machine; - connection to mains electricity supply shall not result in the starting of working parts of a machine.	P			
6.2.11.3	Starting/stopping of a mechanism				
	The primary action for <u>starting</u> or accelerating the <u>movement</u> of a mechanism should be performed <u>by</u> the application or an <u>increase of voltage or fluid pressure</u> , or — if binary logic elements are considered — by passage from state 0 to state 1 (where state 1 represents the highest energy state).	P			
	The primary action for <u>stopping</u> or slowing down should be <u>performed by removal or reduction of voltage</u> or fluid pressure, or — if binary logic elements are considered — by passage from state 1 to state 0 (where state 1 represents the highest energy state).	P			
	In certain applications, such as high-voltage switchgear, <u>this principle cannot be followed</u> , in which case <u>other measures</u> should be <u>applied</u> to achieve the same level of confidence for the stopping or slowing down.			N/A	
	<u>When</u> , in order for the operator to maintain permanent control of deceleration, <u>this principle is not observed</u> (for example, a hydraulic braking device of a self-propelled mobile machine), the <u>machine</u> shall be <u>equipped</u> with a means of <u>slowing and stopping in case of failure</u> of the main braking system.			N/A	

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6.2.11.4	Restart after power interruption				
	If a <u>hazard</u> could be generated, the spontaneous restart of a machine when it is re-energized after power interruption shall be <u>prevented</u> (for example, by use of a self-maintained relay, contactor or valve).	P			
6.2.11.5	Interruption of power supply				
	Machinery shall be designed to <u>prevent hazardous situations resulting from interruption or excessive fluctuation of the power supply</u> . At least the following requirements shall be met:				
	- the <u>stopping</u> function of the machinery <u>shall remain</u> ;	P			
	- all <u>devices</u> whose permanent operation is required <u>for safety shall operate</u> in an effective way to maintain safety (for example, locking, clamping devices, cooling or heating devices, power-assisted steering of self-propelled mobile machinery);			N/A	
	- <u>parts</u> of machinery or workpieces and/or loads held by machinery which are <u>liable to move</u> as a result of potential energy shall be retained for the time necessary to allow them to be <u>safely lowered</u> .	P			
6.2.11.6	Use of automatic monitoring				
	Automatic monitoring is intended to ensure that a safety function or functions implemented by a protective measure do not fail to be performed if the ability of a component or an element to perform its function is diminished, or if the process conditions are changed such that hazards are generated.				
	Automatic monitoring either <u>detects a fault immediately or carries out periodic checks</u> so that a fault is detected before the next demand upon the safety function. In either case, the <u>protective measure</u> can be <u>initiated immediately</u> or delayed until a specific event occurs (for example, the beginning of the machine cycle). The protective measure may be, for example, - the <u>stopping</u> of the hazardous <u>process</u> , - <u>preventing the restart</u> of this process after the first stop following the failure, or - the <u>triggering</u> of an <u>alarm</u> .			N/A	

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6.2.11.7	Safety functions implemented by programmable electronic control systems				
6.2.11.7.1	General The programmable electronic control system should be installed and <u>validated to ensure</u> that the specified <u>performance</u> [for example, safety integrity level (SIL) in IEC 61508] <u>for each safety function</u> has been achieved. Validation comprises testing and analysis (for example, static, dynamic or failure analysis) to show that all parts interact correctly to perform the safety function and that unintended functions do not occur.				
6.2.11.7.2	Hardware aspects The hardware (including, for example, sensors, actuators and logic solvers) shall be selected, and/or <u>designed and installed, to meet</u> both the functional and performance requirements of the safety function(s) to be performed, in particular, by means of				
	- <u>architectural constraints</u> (the configuration of the system, its ability to tolerate faults, its behaviour on detection of a fault, etc.),	P			
	- selection, and/or design, of <u>equipment and devices with an appropriate probability of dangerous random hardware failure</u> , and	P			
	- the incorporation of measures and techniques within the hardware so as to <u>avoid systematic failures</u> and control systematic faults.	P			
6.2.11.7.3	Software aspects The software, including internal operating software (or system software) and application software, shall be <u>designed so as to satisfy the performance specification for the safety functions</u> (see also IEC 61508-3).				
	Application software should <u>not</u> be <u>reprogrammable</u> by the user. This may be achieved by use of embedded software in a non-reprogrammable memory [for example, micro-controller, application-specific integrated circuit (ASIC)].			N/A	
	When the application requires <u>reprogramming by</u> the user, the <u>access</u> to the software dealing with safety functions should be <u>restricted</u> (for example, by locks or passwords for the authorized persons).			N/A	
6.2.11.8	Principles relating to manual control These are as follows.				
	a) Manual control devices shall be <u>designed and located</u> according to the relevant <u>ergonomic principles</u> given in 6.2.8, item f).	P			
	b) A <u>stop control device</u> shall be placed <u>near each start control device</u> . Where the start/stop function is performed by means of a hold-to-run control, a separate stop control device shall be provided when a risk can result from the hold-to-run control device failing to deliver a stop command when released.	P			

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	c) <u>Manual controls</u> shall be <u>located out of reach of the danger zones</u> (see IEC 61310-3), except for certain controls where, of necessity, they are located within a danger zone, such as emergency stop or teach pendant.	P			
	d) Whenever possible, <u>control devices</u> and control positions shall be <u>located so that the operator is able to observe the working area</u> or hazard zone. 1) The driver of a <u>ride-on mobile machine</u> shall be <u>able to actuate all control devices</u> required to operate the machine <u>from the driving position</u> , except for functions which can be controlled more safely from other positions. 2) <u>On machinery intended for lifting persons</u> , <u>controls</u> for lifting and lowering and, if appropriate, for moving the carrier shall generally be <u>located in the carrier</u> . If safe operation requires controls to be situated outside the carrier, the operator in the carrier shall be provided with the means of preventing hazardous movements.	P			
	e) <u>If it is possible to start the same hazardous element by means of several controls</u> , the control circuit shall be so arranged that <u>only one control</u> is <u>effective at a given time</u> . This applies especially to machines which can be manually controlled by means of, among others, a portable control unit (such as a teach pendant), with which the operator can enter danger zones.			N/A	
	f) <u>Control actuators</u> shall be <u>designed or guarded so that their effect</u> , where a risk is involved, <u>cannot occur without intentional operation</u> (see ISO 9355-1, ISO 9355-3 and ISO 447).	P			
	g) For <u>machine functions whose safe operation depends on permanent</u> , direct <u>control</u> by the operator, measures shall be implemented to <u>ensure the presence of the operator</u> at the control position (for example, by the design and location of control devices).	P			
	h) <u>For cableless control</u> , an <u>automatic stop</u> shall be performed <u>when correct control signals</u> are <u>not received</u> , including loss of communication (see IEC 60204-1).			N/A	

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6.2.11.9	Control mode for setting, teaching, process changeover, fault-finding, cleaning or maintenance				
	Where, for setting, teaching, process changeover, fault-finding, cleaning or maintenance of machinery, a guard has to be displaced or removed and/or a protective device has to be disabled, and where it is necessary for the purpose of these operations for the machinery or part of the machinery to be put into operation, the safety of the operator shall be achieved using a specific control mode which simultaneously				
	a) <u>disables all other control modes,</u>			N/A	
	b) <u>permits operation</u> of the hazardous elements <u>only by continuous actuation</u> of an enabling device, a two-hand control device or a hold-to-run control device,			N/A	
	c) <u>permits operation</u> of the hazardous elements <u>only in reduced risk conditions</u> (for example, reduced speed, reduced power/force, step-by-step, for example, with a limited movement control device), and			N/A	
	d) <u>prevents any operation of hazardous functions</u> by voluntary or involuntary action on the machine's sensors.			N/A	
	NOTE For some special machinery other protective measures can be appropriate. This control mode shall be associated with one or more of the following measures: <ul style="list-style-type: none"> - restriction of access to the danger zone as far as possible; - emergency stop control within immediate reach of the operator; portable control unit (teach pendant) and/or local controls (allowing sight of the controlled elements).				
6.2.11.10	Selection of control and operating modes				
	<u>If</u> machinery has been designed and built to allow for its use in <u>several control</u> or <u>operating modes</u> requiring different protective measures and/or work procedures (for example, to allow for adjustment, setting, maintenance, inspection), it shall be fitted with a mode selector which can be locked in each position. <u>Each position</u> of the selector shall be clearly <u>identifiable and</u> shall <u>exclusively allow one</u> control or operating mode.				
	The selector may be replaced by another selection means which <u>restricts</u> the use of <u>certain functions of the machinery to certain</u> categories of <u>operators</u> (for example, access codes for certain numerically controlled functions).				
6.2.11.11	Applying measures to achieve electromagnetic compatibility (EMC)				
	For guidance on electromagnetic compatibility, see IEC 60204-1 and IEC 61000-6.	P			See Job no.3123162

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6.2.11.12	Provision of diagnostic systems to aid fault-finding				
	Diagnostic systems to aid fault-finding <u>should be included in the control system</u> so that there is no need to disable any protective measure. NOTE Such systems not only improve availability and maintainability of machinery, they also reduce the exposure of maintenance staff to hazards.			N/A	
6.2.12	Minimizing probability of failure of safety functions				
6.2.12.1	General Safety of machinery is not only dependent on the reliability of the control systems but also on the reliability of all parts of the machine.				
6.2.12.2	Use of reliable components				
	<p>“Reliable components” means components which are <u>capable of withstanding all disturbances</u> and stresses associated with the usage of the equipment in the conditions of intended use (including the environmental conditions), for the period of time or the number of operations fixed for the use, with a low probability of failures generating a hazardous malfunctioning of the machine. Components shall be selected taking into account all factors mentioned above (see also 6.2.13).</p> <p>NOTE 1 “Reliable components” is not a synonym for “well-tried components” (see ISO 13849-1:2006, 6.2.4).</p> <p>NOTE 2 Environmental conditions for consideration include impact, vibration, cold, heat, moisture, dust, corrosive and/or abrasive substances, static electricity and magnetic and electric fields. Disturbances which can be generated by those conditions include insulation failures and temporary or permanent failures in the function of control system components.</p>	P			The switch has certificate

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6.2.12.3	Use of “oriented failure mode” components				
	<p>“Oriented failure mode” components or systems are those in which the <u>predominant failure mode is known</u> in advance and which can be used so that the effect of such a failure on the machine function can be predicted.</p> <p>NOTE In some cases, it will be necessary to take additional measures to limit the negative effects of such a failure.</p> <p>The use of such components should always be considered, particularly in cases where redundancy (see 6.2.12.4) is not employed.</p>	P			
6.2.12.4	Duplication (or redundancy) of components or subsystems				
	<u>In the design of safety-related parts</u> of the machine, duplication (or redundancy) of components may be used so that, <u>if one component fails, another component</u> or components continue to <u>perform the respective function(s)</u> , thereby ensuring that the safety function remains available.			N/A	
	In order to allow the proper action to be initiated, <u>component failure shall be detected by automatic monitoring</u> (see 6.2.11.6) or in some circumstances by regular inspection, provided that the inspection interval is shorter than the expected lifetime of the components.			N/A	
	Diversity of <u>design</u> and/or technology can be used <u>to avoid common cause failures</u> (for example, from electromagnetic disturbance) or common mode failures.			N/A	
6.2.13	Limiting exposure to hazards through reliability of equipment				
	<p><u>Increased reliability</u> of all component parts of machinery <u>reduces the frequency of incidents</u> requiring intervention, thereby reducing exposure to hazards.</p> <p>This applies to power systems (operative part, see Annex A) as well as to control systems, and to safety functions as well as to other functions of machinery.</p> <p>Safety-related components (for example, certain sensors) of known reliability shall be used.</p> <p>The elements of guards and of protective devices shall be especially reliable, as their failure can expose persons to hazards, and also because poor reliability would encourage attempts to defeat them.</p>	P			

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.2.14	Limiting exposure to hazards through mechanization or automation of loading (feeding)/unloading (removal) operations				
	<p>Mechanization and <u>automation of machine loading/unloading operations and</u>, more generally, of <u>handling operations</u> — of workpieces, materials or substances — limits the risk generated by these operations by reducing the exposure of persons to hazards at the operating points.</p> <p>Automation can be achieved by, for example, robots, handling devices, transfer mechanisms and air-blast equipment. Mechanization can be achieved by, for example, feeding slides, push-rods and hand-operated indexing tables.</p>			N/A	
	<p>While automatic feeding and removal devices have much to offer in preventing accidents to machine operators, they can create danger when any faults are being corrected. Care shall be taken to ensure that the use of <u>these devices does not introduce further hazards</u>, such as trapping or crushing, between the devices and parts of the machine or workpieces/materials being processed. Suitable safeguards (see 6.3) shall be provided if this cannot be ensured.</p>			N/A	
	<p>Automatic <u>feeding and removal devices</u> with their own control systems and the control system of the associated machine <u>shall be interconnected</u> after thorough study of how all safety functions are performed in all the control and operation modes of the entire equipment.</p>			N/A	
6.2.15	Limiting exposure to hazards through location of setting and maintenance points outside danger zones				
	<p>The need for access to danger zones shall be minimized by locating maintenance, lubrication and setting points outside these zones.</p>			N/A	
6.3	Safeguarding and complementary protective measures				
6.3.1	General				
	<p>Guards and protective devices shall be used to protect persons whenever an inherently safe design measure does not reasonably make it possible either to remove hazards or to sufficiently reduce risks. Complementary protective measures involving additional equipment (for example, emergency stop equipment) may have to be implemented.</p> <p>Certain safeguards may be used to avoid exposure to more than one hazard.</p> <p>EXAMPLE A fixed guard preventing access to a zone where a mechanical hazard is present used to reduce noise levels and collect toxic emissions.</p>				
6.3.2	Selection and implementation of guards and protective devices				

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.3.2.1	General The exact choice of a safeguard for a particular machine shall be made on the basis of the risk assessment for that machine.				
6.3.2.2	Where access to the hazard zone is not required during normal operation				
	<p>Where access to the <u>hazard zone</u> is <u>not required</u> during normal operation of the machinery, <u>safeguards should be</u> selected from the following:</p> <p>a) <u>fixed</u> guards (see also ISO 14120);</p> <p>b) <u>interlocking</u> guards with or without guard locking (see also 6.3.3.2.3, ISO 14119 and ISO 14120);</p> <p>c) <u>self-closing</u> guards (see ISO 14120:2002, 3.3.2);</p> <p>d) <u>sensitive protective equipment</u>, such as electrosensitive protective equipment (see IEC 61496) or pressure-sensitive protective devices (see ISO 13856).</p>	P			Fix guard
6.3.2.3	Where access to the hazard zone is required during normal operation				
	<p>Where access to the <u>hazard zone</u> is <u>required</u> during normal operation of the machinery, <u>safeguards should be</u> selected from the following:</p> <p>a) <u>interlocking</u> guards with or without guard locking (see also ISO 14119, ISO 14120 and 6.3.3.2.3 of this document);</p> <p>b) <u>sensitive protective equipment</u>, such as electrosensitive protective equipment (see IEC 61496);</p> <p>c) <u>adjustable</u> guards;</p> <p>d) <u>self-closing</u> guards (see ISO 14120:2002, 3.3.2);</p> <p>e) <u>two-hand control</u> devices (see ISO 13851);</p> <p>f) <u>interlocking</u> guards with a start function (control guard) (see 6.3.3.2.5).</p>			N/A	
6.3.2.4	Where access to the hazard zone is required for machine setting, teaching, process changeover, fault-finding, cleaning or maintenance				
	<p>As far as possible, machines shall be designed so that the <u>safeguards</u> provided for the protection of the production operator <u>also ensure the protection of personnel carrying out setting, teaching, process changeover, fault-finding, cleaning or maintenance</u>, without hindering them in the performance of their task.</p> <p>Such tasks shall be identified and considered in the risk assessment as parts of the use of the machine (see 5.2).</p> <p>NOTE Isolation and energy dissipation for machine shut-down (see 6.3.5.4, and also ISO 14118:2000, 4.1 and Clause 5) ensure the highest level of safety when carrying out tasks (especially maintenance and repair tasks) that do not require the machine to remain connected to its power supply.</p>	P			

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.3.2.5	Selection and implementation of sensitive protective equipment				
6.3.2.5.1	<p>Selection Due to the great diversity of the technologies on which their detection function is based, all types of sensitive protective equipment are far from being equally suitable for safety applications. The following provisions are intended to provide the designer with criteria for selecting, for each application, the most suitable device(s).</p> <p>Types of sensitive protective equipment include</p> <ul style="list-style-type: none"> - light curtains, - scanning devices, for example, laser scanners, - pressure-sensitive mats, and - trip bars, trip wires. <p>Sensitive protective equipment can be used</p> <ul style="list-style-type: none"> - for tripping purposes, - for presence sensing, - for both tripping and presence sensing, or - to re-initiate machine operation - a practice subject to stringent conditions. <p>NOTE Some types of sensitive protective equipment can be unsuitable either for presence sensing or for tripping purposes.</p> <p>The following characteristics of the machinery, among others, can preclude the sole <u>use of sensitive protective equipment</u>:</p> <ul style="list-style-type: none"> - <u>tendency</u> for the machinery <u>to eject materials or component parts</u>; - necessity to guard against <u>emissions</u> (noise, radiation, dust, etc.); - <u>erratic or excessive machine stopping time</u>; <p><u>inability of a machine to stop part-way through a cycle.</u></p>				

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.3.2.5.2	Implementation				
	<p><u>Consideration</u> should be given to</p> <p>a) the <u>size, characteristics and positioning of the detection zone</u> (see ISO 13855, which deals with the positioning of some types of sensitive protective equipment),</p> <p>b) the <u>reaction</u> of the device <u>to fault</u> conditions (see IEC 61496 for electrosensitive protective equipment),</p> <p>c) the <u>possibility of circumvention</u>, and</p> <p>d) <u>detection capability and its variation</u> over the course of time (as a result, for example, of its susceptibility to different environmental conditions such as the presence of reflecting surfaces, other artificial light sources and sunlight or impurities in the air).</p> <p>NOTE 1 IEC 61496 defines the detection capability of electrosensitive protective equipment.</p>			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
	<p>Sensitive protective <u>equipment</u> shall be <u>integrated in the operative part</u> and associated with the control system of the machine <u>so that</u></p> <ul style="list-style-type: none"> - a <u>command is given as soon as</u> a person or part of a <u>person is detected</u>, - the <u>withdrawal of the person</u> or part of a person <u>detected does not</u>, by itself, <u>restart</u> the hazardous <u>machine</u> function(s), and therefore the command given by the sensitive protective equipment is maintained by the control system until a new command is given, - <u>restarting</u> the hazardous machine function(s) <u>results from</u> the <u>voluntary actuation</u> by the operator of a control device placed outside the hazard zone, where this zone can be observed by the operator, - the <u>machine cannot operate during interruption of the detection function</u> of the sensitive protective equipment, except during muting phases, and - the position and the shape of the <u>detection field prevents</u>, possibly together with fixed guards, <u>a person</u> or part of a person <u>from entering</u> or being present <u>in the hazard zone without being detected</u>. <p>NOTE 2 Muting is the temporary automatic suspension of a safety function(s) by safety-related parts of the control system (see ISO 13849-1).</p> <p>For detailed consideration of the fault behaviour of, for example, active optoelectronic protective devices, IEC 61496 should be taken into account.</p>			N/A	
6.3.2.5.3	Additional requirements for sensitive protective equipment when used for cycle initiation				
	<p>In this exceptional application, the <u>starting of the machine cycle is initiated by the withdrawal of a person</u> or of the detected part of a person <u>from the sensing field</u> of the sensitive protective equipment, without any additional start command, hence deviating from the general requirement given in the second point of the dashed list in 6.3.2.5.2, above. <u>After switching on the power supply, or when the machine has been stopped by the tripping function</u> of the sensitive protective equipment, the machine cycle shall be <u>initiated only by voluntary actuation of a start control</u>.</p>			N/A	
	Cycle initiation by sensitive protective equipment shall be subject to the following <u>conditions</u> :				
	a) only active optoelectronic protective devices (AOPDs) <u>complying with IEC 61496 series</u> shall be used;			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
	b) the requirements for an AOPD used <u>as a tripping and presence-sensing device</u> (see IEC 61496) are <u>satisfied</u> — in particular, location, minimum distance (see ISO 13855), detection capability, reliability and monitoring of control and braking systems;			N/A	
	c) the <u>cycle time of the machine is short</u> and the facility to <u>re-initiate</u> the machine upon clearing of the sensing field is <u>limited to a period</u> commensurate with a single normal cycle;			N/A	
	d) <u>entering the sensing field</u> of the AOPD(s) <u>or opening interlocking guards</u> is the <u>only way to enter the hazard zone</u> ;			N/A	
	e) <u>if there is more than one AOPD</u> safeguarding the machine, <u>only one</u> of the AOPDs is <u>capable of cycle re-initiation</u> ;			N/A	
	f) with regard to the higher risk resulting from automatic cycle initiation, the AOPD and the associated control <u>system comply with a higher safety-related performance than under normal conditions.</u> NOTE 1 The hazard zone as referred to in d) is any zone where the hazardous function (including ancillary equipment and transmission elements) is initiated by clearing of the sensing field. NOTE 2 See also IEC/TS 62046.			N/A	
6.3.2.6	Protective measures for stability				
	<u>If stability cannot be achieved by inherently safe design measures</u> such as weight distribution (see 6.2.6), it shall be maintained by the <u>use of protective measures such as</u> <ul style="list-style-type: none"> - anchorage <u>bolts</u>, - <u>locking devices</u>, - <u>movement limiters</u> or mechanical stops, - <u>acceleration</u> or deceleration <u>limiters</u>, - <u>load limiters</u>, and - <u>alarms</u> warning of the approach to stability or tipping limits. 			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.3.3	Requirements for design of guards and protective devices				
6.3.3.1	General requirements				
	Guards and protective devices shall be designed to be suitable for the intended use, taking into account mechanical and other hazards involved. Guards and protective devices shall be compatible with the working environment of the machine and designed so that they cannot be easily defeated. They shall provide the minimum possible interference with activities during operation and other phases of machine life, in order to reduce any incentive to defeat them. NOTE For additional information, see ISO 14120, ISO 13849-1, ISO 13851, ISO 14119, ISO 13856, IEC 61496 and IEC 62061.	P			
	Guards and protective devices shall a) be of <u>robust construction</u> , b) <u>not give rise</u> to any <u>additional hazard</u> , c) <u>not be easy to bypass</u> or render non-operational, d) be located <u>at an adequate distance from the danger zone</u> (see ISO 13855 and ISO 13857), e) cause <u>minimum obstruction to the view of the production process</u> , and f) <u>enable essential work</u> to be carried out for the installation and/or replacement of tools and for maintenance by allowing access only to the area where the work has to be carried out — if possible, without the guard having to be removed or protective device having to be disabled. For openings in the guards, see ISO 13857.	P			Robust construction
6.3.3.2	Requirements for guards				
6.3.3.2.1	Functions of guards				
	The functions that guards can achieve are - prevention of access to the space enclosed by the guard, and/or - containment/capture of materials, workpieces, chips, liquids which can be ejected or dropped by the machine, and reduction of emissions (noise, radiation, hazardous substances such as dust, fumes, gases) that can be generated by the machine. Additionally, they could need to have particular properties relating to electricity, temperature, fire, explosion, vibration, visibility (see ISO 14120) and operator position ergonomics (for example, usability, operator's movements, postures, repetitive movements).				

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.3.3.2.2	Requirements for fixed guards				
	Fixed guards shall be securely <u>held in place</u> either <ul style="list-style-type: none"> - <u>permanently</u> (for example by welding), or - <u>by means of fasteners</u> (screws, nuts) making removal/opening impossible without using tools; they should not remain closed without their fasteners (see ISO 14120). NOTE A fixed guard can be hinged to assist in its opening.	P			By means of fastener
6.3.3.2.3	Requirements for movable guards				
	Movable <u>guards</u> which provide protection against hazards generated by <u>moving transmission parts</u> shall <ul style="list-style-type: none"> a) as far as possible <u>when open remain fixed to the machinery</u> or other structure (generally by means of hinges or guides), and b) be interlocking (with guard locking when necessary) (see ISO 14119). Movable <u>guards</u> against hazards generated by <u>non-transmission moving parts</u> shall be designed and associated with the machine control system so that <ul style="list-style-type: none"> - <u>moving parts cannot start up</u> while they <u>are within the operator's reach and the operator cannot reach moving parts once they have started up</u>, with this able to be achieved by interlocking guards, with guard locking when necessary, - they can be <u>adjusted only by an intentional action</u>, such as the use of a tool or a key, and - the <u>absence or failure</u> of one of their components either <u>prevents starting of the moving parts or stops</u> them, with this able to be achieved by automatic monitoring (see 6.2.11.6). See Figure 4 and ISO 14119.			N/A	
6.3.3.2.4	Requirements for adjustable guards				
	Adjustable guards may only be used <u>where the hazard zone cannot</u> for operational reasons <u>be completely enclosed</u> . Manually adjustable guards <u>shall be</u> <ul style="list-style-type: none"> - designed so that the <u>adjustment remains fixed</u> during a given operation, and - readily <u>adjustable without</u> the use of <u>tools</u>. 			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
	Requirements for interlocking guards with a start function (control guards)				
	An interlocking guard with a start function may only be used provided that				
	a) all <u>requirements for interlocking guards</u> are satisfied (see ISO 14119),			N/A	
	b) the <u>cycle time of the machine</u> is short,			N/A	
	c) the <u>maximum opening time of the guard is preset to a low value</u> (for example, equal to the cycle time) and, when this time is exceeded, the hazardous function(s) cannot be initiated by the closing of the interlocking guard with a start function and resetting is necessary before restarting the machine,			N/A	
	d) the dimensions or <u>shape of the machine do not allow a person</u> , or part of a person, <u>to stay in the hazard zone</u> or between the hazard zone and the guard while the guard is closed (see ISO 14120),			N/A	
	e) <u>all other guards</u> , whether fixed (removable type) or movable, <u>are interlocking guards</u> ,			N/A	
	f) the interlocking device associated with the interlocking guard with a start function is designed such that — for example, by duplication of position detectors and use of automatic monitoring (see 6.2.11.6) — <u>its failure cannot lead to an unintended/unexpected start-up</u> , and			N/A	
	g) the guard is securely held open (for example, by a spring or counterweight) such that it cannot initiate a start while falling by its own weight.			N/A	
6.3.3.2.6	Hazards from guards				
	Care shall be taken to prevent hazards which could be generated by				
	- the <u>guard construction</u> (sharp edges or corners, material, noise emission, etc.),	P			
	- the <u>movements of the guards</u> (shearing or crushing zones generated by power-operated guards and by heavy guards which are liable to fall).			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.3.3.3	Technical characteristics of protective devices				
	Protective devices shall be selected or designed and connected to the control system such that <u>correct implementation of their safety function(s) is ensured</u> .			N/A	
	Protective devices shall be selected on the basis of their having <u>met the appropriate product standard</u> (for example, IEC 61496 for active optoelectronic protective devices) or shall be designed according to one or several of the principles formulated in ISO 13849-1 or IEC 62061.			N/A	
	Protective devices shall be installed and connected to the control system so that they <u>cannot be easily defeated</u> .			N/A	
6.3.3.4	Provisions for alternative types of safeguards				
	Provisions should be made to <u>facilitate the fitting of alternative types of safeguards</u> on machinery where it is known that it will be necessary to change the safeguards because of the range of work to be carried out.			N/A	
6.3.4	Safeguarding to reduce emissions				
6.3.4.1	General If the measures for the reduction of emissions at source specified in 6.2.2.2 are not adequate, the machine shall be provided with <u>additional protective measures</u> (see 6.3.4.2 to 6.3.4.5).				
6.3.4.2	Noise				
	Additional protective measures against noise include <ul style="list-style-type: none"> - <u>enclosures</u> (see ISO 15667), - <u>screens</u> fitted to the machine, and - <u>silencers</u> (see ISO 14163). 			N/A	
6.3.4.3	Vibration				
	Additional protective measures against vibration include <ul style="list-style-type: none"> - vibration <u>isolators</u>, such as <u>damping devices</u> placed between the source and the exposed person, - <u>resilient mounting</u>, and - <u>suspended seats</u>. For measures for vibration isolation of stationary industrial machinery see EN 1299.			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.3.4.4	Hazardous substances				
	Additional protective measures against hazardous substances include <ul style="list-style-type: none"> - <u>encapsulation of the machine</u> (enclosure with negative pressure), - local exhaust <u>ventilation with filtration</u>, - <u>wetting with liquids</u>, and - <u>special ventilation</u> in the area of the machine (air curtains, cabins for operators). 			N/A	
6.3.4.5	Radiation				
	Additional protective measures against radiation include <ul style="list-style-type: none"> - use of <u>filtering and absorption</u>, and - use of <u>attenuating screens or guards</u>. 			N/A	
6.3.5	Complementary protective measures				
6.3.5.1	General Protective measures which are neither inherently safe design measures, nor safeguarding (implementation of guards and/or protective devices), nor information for use, could have to be implemented as required by the intended use and the reasonably foreseeable misuse of the machine.				
6.3.5.2	Components and elements to achieve emergency stop function If, following a risk assessment, a machine needs to be fitted with components and elements to achieve an emergency stop function for enabling actual or impending emergency situations to be averted, the following requirements apply:				
	- the <u>actuators</u> shall be <u>clearly identifiable</u> , clearly visible and readily accessible;	P			
	- the <u>hazardous process</u> shall be <u>stopped as quickly as possible</u> without creating additional hazards, but if this is not possible or the risk cannot be reduced, it should be questioned whether implementation of an emergency stop function is the best solution;	P			
	- the <u>emergency stop control shall trigger</u> or permit the triggering of certain safeguard movements where necessary.			N/A	
	Once active operation of the <u>emergency stop</u> device has ceased following an emergency stop command, the effect of this command shall be <u>sustained until</u> it is <u>reset</u> . This reset shall be possible only at the location where the emergency stop command has been initiated. The reset of the device shall not restart the machinery, but shall only permit restarting.			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.3.5.3	Measures for the escape and rescue of trapped persons				
	Measures for the escape and rescue of trapped persons may consist, among others, of - <u>escape routes</u> and shelters in installations generating operator-trapping hazards, - <u>arrangements for moving some elements by hand</u> , after an emergency stop, - <u>arrangements for reversing the movement of some elements</u> , - <u>anchorage points</u> for descender devices, - <u>means of communication</u> to enable trapped operators to call for help.			P	
6.3.5.4	Measures for isolation and energy dissipation Machines shall be equipped with the technical means to achieve isolation from power supply(ies) and dissipation of stored energy by means of the following actions:				
	a) <u>isolating</u> (disconnecting, separating) <u>the machine</u> (or defined parts of the machine) <u>from all power supplies</u> ;	P			Turn off the switch can cut off the electric power
	b) <u>locking</u> (or otherwise securing) <u>all the isolating units</u> in the isolating position;			N/A	
	c) <u>dissipating or</u> , if this is not possible or practicable, <u>restraining</u> (containing) <u>any stored energy</u> which can give rise to a hazard;			N/A	
	d) <u>verifying</u> , by means of safe working procedures, <u>that the actions taken</u> according to a), b) and c) above have <u>produced the desired effect</u> . See ISO 14118:2000, Clause 5, and IEC 60204-1:2005, 5.5 and 5.6.	P			
6.3.5.5	Provisions for easy and safe handling of machines and their heavy component parts				
	Machines and their component parts which cannot be moved or transported by hand shall be provided or be capable of being provided with suitable attachment devices for transport by means of lifting gear. These attachments may be, among others, - <u>standardized lifting appliances</u> with slings, hooks, eyebolts, or tapped holes for appliance fixing, - appliances for <u>automatic grabbing with a lifting hook</u> when attachment is not possible from the ground, - <u>fork locating devices</u> for machines to be transported by a lift truck, - <u>lifting and stowing gear</u> and appliances <u>integrated into the machine</u> . <u>Parts</u> of machinery which can be removed manually in operation <u>shall be provided with means for their safe removal and replacement</u> .			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.3.5.6	Measures for safe access to machinery				
	Machinery shall be so designed as to enable <u>operation</u> and all routine tasks relating to setting and/or maintenance to be carried out as far as possible <u>by a person remaining at ground level</u> . <u>Where</u> this is <u>not possible</u> , machines shall have <u>built-in platforms, stairs or other facilities</u> to provide safe access for those tasks; however, care should be taken to ensure that such platforms or stairs do not give access to danger zones of machinery.			N/A	
	The <u>walking areas</u> shall be made from materials which remain as slip resistant as <u>practicable under working conditions</u> and, depending on the height from the ground, shall be provided with suitable guard-rails (see ISO 14122-3). In large automated installations, particular attention shall be given to safe means of access, such as walkways, conveyor bridges or crossover points.			N/A	
	Means of access to parts of machinery located <u>at height</u> shall be provided with collective <u>means of protection against falls</u> (for example, guard-rails for stairways, stepladders and platforms and/or safety cages for ladders). As necessary, anchorage points for personal protective equipment against falls from height shall also be provided (for example, in carriers of machinery for lifting persons or with elevating control stations).			N/A	
	<u>Openings</u> shall, whenever possible, open <u>towards a safe position</u> . They shall be designed to prevent hazards due to unintended opening.			N/A	
	The necessary <u>aids for access</u> shall be provided (steps, handholds, etc.). <u>Control devices</u> shall be <u>designed</u> and located to <u>prevent their being used as aids for access</u> .			N/A	
	When <u>machinery for lifting</u> goods and/or persons includes landings at fixed levels, these shall be equipped <u>with interlocking guards</u> for preventing falls when the platform is not present at a level. Movement of the lifting platform shall be prevented while the guards are open.			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.4	Information for use				
6.4.1	General requirements				
6.4.1.1	Drafting information for use is an integral part of the design of a machine (see Figure 2). Information for use consists of communication links, such as texts, words, signs, signals, symbols or diagrams, used separately or in combination to convey information to the user. Information for use is intended for professional and/or non-professional users.				
6.4.1.2	Information shall be provided to the user about the <u>intended use of the machine</u> , taking into account, notably, all its operating modes. The information shall contain <u>all directions</u> required <u>to ensure</u> safe and <u>correct use</u> of the machine. With this in view, it shall <u>inform</u> and warn <u>the user about residual risk</u> . The information <u>shall indicate</u> , as appropriate, <ul style="list-style-type: none"> - the <u>need for training</u>, - the <u>need for personal protective equipment</u>, and - the possible <u>need for additional</u> guards or protective <u>devices</u>. It shall not exclude uses of the machine that can reasonably be expected from its designation and description and shall also warn about the risk which would result from using the machine in other ways than the ones described in the information, especially considering its reasonably foreseeable misuse.	P			
6.4.1.3	Information for use <u>shall cover</u> , separately or in combination, <u>transport, assembly and installation, commissioning, use</u> of the machine (setting, teaching/programming or process changeover, operation, cleaning, fault-finding and maintenance) and, if necessary, <u>dismantling, disabling and scrapping</u> .	P			

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.4.2	Location and nature of information for use				
	Depending on the risk, the time when the information is needed by the user and the machine design, it shall be decided whether the information — or parts thereof — are to be given a) in/on the machine itself (see 6.4.3 and 6.4.4), b) in accompanying documents (in particular instruction handbook, see 6.4.5), c) on the packaging, d) by other means such as signals and warnings outside the machine. Standardized phrases shall be considered where important messages such as warnings are given	P			
6.4.3	Signals and warning devices Visual signals, such as flashing lights and audible signals such as sirens may be used <u>to warn of an impending hazardous event</u> such as machine start-up or overspeed. Such signals may also be used to warn the operator before the triggering of automatic protective measures (see 6.3.2.7).				
	It is essential that these signals a) be <u>emitted before</u> the occurrence of the hazardous event, b) be <u>unambiguous</u> , c) be <u>clearly perceived</u> and differentiated from all other signals used, and d) be <u>clearly recognized</u> by the operator and other persons.			N/A	
	The warning devices shall be designed and <u>located such that checking is easy</u> . The information for use shall prescribe regular checking of warning devices. The attention of designers is drawn to the possibility of “sensorial saturation”, which can result from too many visual and/or acoustic signals and which can also lead to defeating the warning devices.			N/A	
6.4.4	Markings, signs (pictograms) and written warnings Machinery shall bear all markings which are necessary				
	a) for its <u>unambiguous identification</u> , including at least 1) the <u>name and address of the manufacturer</u> , 2) the <u>designation of series or type</u> , and 3) the <u>serial number</u> , if any,	P			

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		PASS	FAIL		
	b) in order to <u>indicate its compliance with mandatory requirements</u> , comprising 1) <u>marking</u> , and 2) written indications, such as the <u>authorized representative</u> of the manufacturer, <u>designation</u> of the machinery, <u>year of construction</u> , and intended <u>use in potentially explosive atmospheres</u> ,	P			
	c) for its <u>safe use</u> , for example, 1) <u>maximum speed</u> of rotating parts, 2) <u>maximum diameter of tools</u> , 3) <u>mass</u> (in kilograms) of the machine itself and/or of removable parts, 4) <u>maximum working load</u> , 5) <u>necessity of wearing personal protective equipment</u> , 6) <u>guard adjustment data</u> , and 7) <u>frequency of inspection</u> .	P			
	<u>Information</u> printed directly on the machine <u>should be permanent</u> and remain legible throughout the expected life of the machine.	P			
	Signs or written warnings indicating only “Danger” shall not be used. Markings, signs and written <u>warnings</u> shall be readily <u>understandable</u> and unambiguous, especially as regards the part of the function(s) of the machine to which they are related. Readily understandable signs (pictograms) should be used in preference to written warnings.	P			
	Signs and pictograms should only be used if they are understood in the culture in which the machinery is to be used. Written warnings shall be drawn up in the <u>language(s) of the country in which the machine will be used</u> for the first time and, on request, in the language(s) understood by operators.	P			
	<u>Markings</u> shall <u>comply with recognized standards</u> (for example, ISO 2972 or ISO 7000, for pictograms, symbols and colours in particular). See IEC 60204-1 as regards marking of electrical equipment. See ISO 4413 and ISO 4414 for hydraulic and pneumatic equipment.	P			

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.4.5	Accompanying documents (in particular — instruction handbook)				
6.4.5.1	Contents The instruction handbook or other written instructions (for example, on the packaging) shall contain, among others, the following:				
	a) information relating to <u>transport</u> , handling and storage of the machine, such as 1) storage conditions for the machine, 2) dimensions, mass value(s), position of the centre(s) of gravity, and 3) indications for handling (for example, drawings indicating application points for lifting equipment);			N/A	
	b) information relating to <u>installation</u> and commissioning of the machine, such as 1) fixing/anchoring and dampening of noise and vibration requirements, 2) assembly and mounting conditions, 3) space needed for use and maintenance, 4) permissible environmental conditions (for example, temperature, moisture, vibration, electromagnetic radiation), 5) instructions for connecting the machine to power supply (particularly on protection against electrical overloading), 6) advice on waste removal/disposal, and 7) if necessary, recommendations related to protective measures which have to be implemented by the user — for example, additional safeguards (see Figure 2, Footnote d), safety distances, safety signs and signals;			N/A	

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
	c) information relating to <u>the machine</u> itself, such as <ol style="list-style-type: none"> 1) detailed description of the machine, its fittings, guards and/or protective devices, 2) the comprehensive range of applications for which the machine is intended, including prohibited usages, if any, taking into account variations of the original machine if appropriate, 3) diagrams (especially schematic representation of safety functions), 4) data on noise and vibration generated by the machine, and on radiation, gases, vapours and dust emitted by it, with reference to the measuring methods (including measurement uncertainties) used, 5) technical documentation of electrical equipment (see IEC 60204), and 6) documents attesting that the machine complies with mandatory requirements; 	P			
	d) information relating to the <u>use</u> of the machine, such as that related to or describing <ol style="list-style-type: none"> 1) intended use, 2) manual controls (actuators), 3) setting and adjustment, 4) modes and means for stopping (especially emergency stop), 5) risks which could not be eliminated by the protective measures implemented by the designer, 6) particular risks which can be generated by certain applications, by the use of certain fittings, and about specific safeguards necessary for such applications, 7) reasonably foreseeable misuse and prohibited applications, 8) fault identification and location, for repair and for restarting after an intervention, and 9) personal protective equipment needed to be used and the training that is required; 	P			

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		PASS	FAIL		
	e) information for <u>maintenance</u> , such as 1) the nature and frequency of inspections for safety functions, 2) specification of the spare parts to be used when these can affect the health and safety of operators, 3) instructions relating to maintenance operations which require a definite technical knowledge or particular skills and hence need to be carried out exclusively by skilled persons (for example, maintenance staff, specialists), 4) instructions relating to maintenance actions (replacement of parts, etc.) which do not require specific skills and hence may be carried out by users (for example, operators), and 5) drawings and diagrams enabling maintenance personnel to carry out their task rationally (especially fault-finding tasks);	P			
	f) information relating to <u>dismantling</u> , disabling and scrapping;			N/A	
	g) information for <u>emergency situations</u> , such as 1) the operating method to be followed in the event of accident or breakdown, 2) the type of fire-fighting equipment to be used, and 3) a warning of possible emission or leakage of hazardous substance(s) and, if possible, an indication of means for fighting their effects;			N/A	
	h) <u>maintenance</u> instructions provided for skilled persons [item e) 3) above] and maintenance instructions provided for unskilled persons [item e) 4) above], that need to appear clearly separated from each other.	P			

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		PASS	FAIL		
6.4.5.2	Production of instruction handbook The following applies to the production and presentation of the instruction handbook.				
	a) The type font and size of print shall ensure the best possible <u>legibility</u> . Safety warnings and/or cautions should be emphasized by the use of colours, symbols and/or large print. b) The information for use shall be given in the <u>language(s) of the country</u> in which the machine will be <u>used for the first time</u> and in the original version. If more than one language is to be used, each should be readily distinguished from another, and efforts should be made to keep the translated text and relevant illustration together. NOTE In some countries the use of specific language(s) is covered by legal requirements. c) Whenever helpful to the understanding, <u>text should be supported by illustrations</u> . These illustrations should be supplemented with written details enabling, for example, manual controls (actuators) to be located and identified. They should <u>not be separated from the</u> accompanying <u>text</u> and should follow sequential operations. d) Consideration should be given to presenting information in tabular form where this will aid understanding. <u>Tables</u> should be adjacent to the relevant text. e) The <u>use of colours</u> should be considered, particularly in relation to components requiring quick identification. f) When information for use is lengthy, a <u>table of contents</u> and/or an index should be provided. g) Safety-relevant instructions which involve immediate action should be provided in a form readily available to the operator.	P			

ITEM	PROVISIONS OF STANDARD ISO 12100:2010	IN COMPLIANCE		NA	COMMENTS
		PASS	FAIL		
6.4.5.3	Drafting and editing information for use The following applies to the drafting and editing of information for use.				
	a) Relationship to model: the <u>information</u> shall clearly <u>relate to the specific model</u> of machine and, if necessary, other appropriate identification (for example, by serial number). b) Communication principles: when information for use is being prepared, the communication process “see – think – use” should be followed in order to achieve the maximum effect and should follow sequential operations. The questions, “How?” and “Why?” should be anticipated and the answers provided. c) <u>Information for use shall be as simple</u> and as brief <u>as possible</u> , and should be expressed in consistent terms and units with a clear explanation of unusual technical terms. d) When it is foreseen that a machine will be put to non-professional use, the instructions should be written <u>in a form that is readily understood by the non-professional user</u> . If personal protective equipment is required for the safe use of the machine, clear advice should be given, for example, on the packaging as well as on the machine, so that this information is prominently displayed at the point of sale. e) <u>Durability and availability of the documents</u> : documents giving instructions for use should be produced in durable form (i.e. they should be able to survive frequent handling by the user). It can be useful to mark them “keep for future reference”. Where information for use is kept in electronic form (CD, DVD, tape, hard disk, etc.), information on safety-related issues that need immediate action shall always be backed up with a hard copy that is readily available.	P			

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		PASS	FAIL		
7	DOCUMENTATION OF RISK ASSESSMENT AND RISK REDUCTION				
	<p>The documentation shall demonstrate the procedure that has been followed and the results that have been achieved. This includes, when relevant, documentation of</p> <ul style="list-style-type: none"> a) the <u>machinery</u> for which the risk assessment has been made (for example, specifications, limits, intended use); b) any <u>relevant assumptions</u> that have been made (loads, strengths, safety factors, etc.); c) the <u>hazards</u> and hazardous situations <u>identified</u> and the hazardous events considered in the risk assessment; d) the information on which risk assessment was based (see 5.2): <ul style="list-style-type: none"> 1) the <u>data used</u> and the sources (accident histories, experience gained from risk reduction applied to similar machinery, etc.); 2) the uncertainty associated with the data used and its impact on the risk assessment; e) the <u>risk reduction objectives</u> to be achieved by protective measures; f) the <u>protective measures implemented</u> to eliminate identified hazards or to reduce risk; g) <u>residual risks</u> associated with the machinery; h) the <u>result of the risk assessment</u>; i) any forms completed during the risk assessment. <p><u>Standards</u> or other specifications used to select protective measures referred to in f) above should be referenced.</p> <p>NOTE No requirement is given in this International Standard to deliver the risk assessment documentation together with the machine. See ISO/TR 14121-2 for information on documentation.</p>	P			

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